

GLMC 1 R & GLMC 2 R

High-performance RTK GNSS receiver designed for unmanned vehicles. Automotive-grade positioning chip, integrated MEMS inertial measurement unit and a functional safety processor. Deeply coupled navigation algorithms, effectively addressing challenges such as satellite signal interference, blockage, and multipath effects.



GLMC 1 R
GNSS Receiver, IMU, Unmanned Vehicles

All constellations &
all frequencies

PPP-B2b, PPP-E6,
SBAS supported

Built-in deeply coupled
navigation algorithm

Heading with dual antenna
(GLMC 2 R only)

Compatibility with
multiple protocols

Safe encrypted data and
cloud management



GLMC 2 R

GNSS Receiver, IMU, Dual Antenna

Heading, Unmanned Vehicles

System

Hardware System ARM Cortex-A7 1.8 GHz

OS Linux

GNSS

GPS (GLMC 1 R) L1 C/A, L1C*, L2, L5

GPS (GLMC 2 R) L1 C/A, L1C*, L2

GLONASS L1, L2

BDS (GLMC 1 R) B1I, B2I, B3I, B1C*, B2a, B2b*(PPP)

BDS (GLMC 2 R) B1I, B2I, B1C*, B2b*(PPP)

GALILEO (GLMC 1 R) E1, E5a, E5b, E6*(PPP)

GALILEO (GLMC 2 R) E1, E5b

QZSS (GLMC 1 R) L1C/A, L2, L5, L6(CLAS*)

QZSS (GLMC 2 R) L1C/A, L1C*, L2

SBAS* (GLMC 1 R only) L1C/A

NavIC (IRNSS)
(GLMC 1 R only) L5*

Channel (GLMC 1 R) 1507
Channel (GLMC 2 R) 1500

Pseudorange Observation
Accuracy (GLMC 1 R only) ≤ 10.0 cm

Carrier Phase Observation
Accuracy (GLMC 1 R only) ≤ 1.0 cm

Single (RMS) Horizontal: 1.5 m / Vertical: 2.5 m

RTK (RMS) Horizontal: $\pm (10 \text{ mm} + 1 \text{ ppm})$
Vertical: $\pm (15 \text{ mm} + 1 \text{ ppm})$

Static Accuracy (RMS)
(GLMC 1 R only) Horizontal: $\pm (2.5 \text{ mm} + 1 \text{ ppm})$
Vertical: $\pm (5 \text{ mm} + 1 \text{ ppm})$

Timing Accuracy (RMS)
(GLMC 1 R only) ≤ 20 ns (does not include delays
caused by RF cables or antennas)

Directional Accuracy (RMS)
(GLMC 2 R only) 0.1°/1 m baseline

Speed Accuracy (RMS)
(GLMC 2 R only) 0.03 m/s

Position Data NMEA-0183

Differential Data (GLMC 1 R) RTCM 3.X

Differential Data (GLMC 2 R) RTCM 3.3

Data Format RINEX, Custom

Data Update Frequency RTK: 1 Hz, 5 Hz, 10 Hz (turn off
integrated navigation)
IMU: 50/100 Hz

IMU

IMU parameters Gyroscope range: $\pm 300^\circ/\text{s}$,
Full temperature zero deviation:
0.3°/s, Scale error: 4%,
Three-axis orthogonal coupling
error: 1.7% (0.1°)

Accelerometer

Measuring range: $\pm 16\text{g}$
Full temperature zero deviation:
5mg, Scale error: 2%
Three-axis orthogonal coupling
error: 0.9% (0.05°)

Inertial Navigation Ability (GLMC 2 R only)

In the situation that failed to track
satellite signal 10 s, RTK can keep
Positioning Accuracy: Horizontal
0.32 m; Vertical 0.2 m Velocity
Accuracy: Horizontal 0.08m/s,
Vertical 0.04m/s, Attitude
Accuracy: roll 0.07°, pitch 0.07°;
azimuth 0.24°

System

Serial port Standard RS232 interface,
Baud rate supports 1200, 2400,
4800, 9600, 19200, 38400,
115200, 230400 bps

USB Integrated on the 7-pin interface,
support access to the computer to
copy data directly

Network port Standard RJ45 interface,
10/100 Mbps network adaptive

Network Communication LTE FDD: B1/2/3/4/5/7/8/12/13/
18/19/20/25/26/28
LTE TDD: B38/39/40/41
WCDMA: B1/2/4/5/6/8/19
GSM: B2/3/5/8

Interface PWE×1: Power supply port,
DATA×1, PPS×1,
SIM×1: Nano SIM card,
Ethernet×1,
4G×1: 4G antenna port, GNSS×1:
main antenna (GLMC 1 R) /
GNSS×2: TCN port (GLMC 2 R)

Storage 32GB, circular storage,
support multi-channel storage

Electrical

Voltage Input 9-24 VDC (12 V typical)

Power Dissipation (GLMC 1 R) 1.8 W (typ)

Power Dissipation (GLMC 2 R) 1.6 W (typ)

Environment

Operating Temperature -40°C to +85°C

Storage Temperature -40°C to +85°C

Ingress Protection IP68

Physical

Material Magnesium alloy main body

Dimension 148.8 × 105 × 50.3 mm

Weight 490 g

* Firmware support is required
Errors and technical modification subject to change.

Contact us

office@general-laser.at

general-laser.at

+43 1 890 2002